

**EXISTENCE OF TRAVELLING WAVES FOR A CLASS  
OF INTEGRO-DIFFERENTIAL EQUATIONS  
FROM POPULATION DYNAMICS**

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**Abstract:** Existence of travelling waves solutions is studied for a class of integro-differential equations arising in population dynamics. The proof of wave existence is based on the Leray-Schauder method which uses topological degree and a priori estimates of the solution.

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**Key Words:** nonlocal reaction-diffusion equations, Fredholm property, properness, topological degree, travelling waves

### 1. Introduction

In this paper we study the existence of travelling wave solutions for integro-differential equations of the form

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + F(u, J(u)), \quad (1.1)$$

where  $J(u)$  is the nonlocal term,

$$J(u) = \int_{-\infty}^{\infty} \phi(x-y) u(y, t) dy, \quad (1.2)$$

$\phi : \mathbb{R} \rightarrow \mathbb{R}$  is a bounded nonnegative function with a compact support,  $\int_{-\infty}^{\infty} \phi(y) dy =$

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$$F(w, J(w)) = f(w)J(w) - g(w).$$

The properties of the functions  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  will be specified below. Equations of this type arise in population dynamics, where  $u$  denotes the density of the population and the integral  $J(u)$  shows that the interaction of the individuals can be nonlocal [4], [6].

Denote  $F_0(w) = F(w, w) = wf(w) - g(w)$ . Suppose that  $f, g \in C^1(\mathbb{R})$  and that equation  $F_0(w) = 0$  has three solutions,  $w^\pm$  and  $w^*$ ,  $w^+ < w^* < w^-$ , with  $F_0'(w^+) < 0$ ,  $F_0'(w^-) < 0$ ,  $F_0'(w^*) > 0$ . This means that, regarded as stationary solutions of the ODE  $dw/dt = wf(w) - g(w)$ ,  $w^+$ ,  $w^-$  are stable, while  $w^*$  is unstable. Therefore,

$$\begin{cases} F_0'(w^\pm) = f(w^\pm) + w^\pm f'(w^\pm) - g'(w^\pm) < 0, \\ F_0'(w^*) = f(w^*) + w^* f'(w^*) - g'(w^*) > 0. \end{cases} \quad (1.3)$$

According to the stability of the points  $w^+$  and  $w^-$  this case is called bistable. It is known that the reaction-diffusion equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + F_0(u)$$

has a travelling wave solution, in this case, with the limits  $w(\pm\infty) = w^\pm$  at  $\pm\infty$ . Moreover, this solution is unique up to a translation and it is globally stable [7]. In the monostable case, where one of the points  $w^+$  and  $w^-$  is unstable, the wave is not unique.

The same classification is used for the integro-differential equations. Equation (1.1) in the bistable case with  $f(w) = w(1-w)$  and  $g(w) = w$  is studied in [3]. Another bistable case was analyzed in [1], for functions  $\phi$  with narrow support.

A travelling wave solution of the nonlocal reaction-diffusion equation (1.1) has the form  $u(x, t) = w(x - ct)$ , where the constant  $c \in \mathbb{R}$  is the wave speed and should be found together with the function  $w$ . They satisfy the equation

$$w'' + cw' + F(w, J(w)) = 0. \quad (1.4)$$

We are interested in solutions of equation (1.4) with the limits

$$w(\pm\infty) = w^\pm, \quad (1.5)$$

where the values  $w^\pm$  are such that  $F(w^\pm, w^\pm) = 0$ .

We will use conventional Hölder spaces  $E = C^{2+\alpha}(\mathbb{R})$ ,  $E^0 = C^\alpha(\mathbb{R})$ , with  $0 < \alpha < 1$ , and weighted Hölder spaces. Let  $\mu(x) = 1 + x^2$  and  $E_\mu$ ,  $E_\mu^0$  be the corresponding weighted spaces endowed with the norms  $\|u\|_\mu = \|\mu u\|_E$  and  $\|u\|_{0\mu} = \|\mu u\|_{E^0}$ .

We need weighted spaces in order to define a topological degree in unbounded domains where the Leray-Schauder degree is not applicable [5]. Since any function  $u \in E_\mu$  has the zero limit at  $\pm\infty$ , we are looking for the solutions  $w$  of (1.4) under the form  $w = u + \psi$ , where  $\psi \in C^\infty(\mathbb{R})$  is chosen such that  $\psi(x) = w^+$  for  $x \geq 1$  and  $\psi(x) = w^-$  for  $x \leq -1$ . Thus equation (1.4) can be written as

$$(u + \psi)'' + c(u + \psi)' + F(u + \psi, J(u + \psi)) = 0. \quad (1.6)$$

Denote by  $A$  the operator in the left-hand side of (1.6), that is  $A : E_\mu \rightarrow E_\mu^0$ ,

$$Au = (u + \psi)'' + c(u + \psi)' + F(u + \psi, J(u + \psi)). \quad (1.7)$$

In order to prove the existence of travelling waves solutions of problem (1.1) we will employ the Leray-Schauder method. To do this, one combines the topological degree constructed in [2] with a priori estimates in weighted spaces which we deduce in the sequel, both for the function  $w$  and the wave velocity  $c(\tau)$ .

Let us briefly recall the Leray-Schauder method. Let  $\mathcal{E}$ ,  $\mathcal{E}_0$  be two Banach spaces,  $A : \mathcal{E} \rightarrow \mathcal{E}_0$  be a given operator, and let  $\Omega$  be a bounded domain from the functions space  $\mathcal{E}$ . To study the existence of solutions of the equation  $Au = 0$  in  $\Omega$ , the following property of the degree is used:

*If there exists a topological degree  $\gamma(A, \Omega)$  associated to  $A$  and  $\Omega$ , and it is different from zero,  $\gamma(A, \Omega) \neq 0$ , then the equation  $Au = 0$  admits at least one solution in the domain  $\Omega$ .*

We construct a continuous deformation of the operator,  $A_\tau$ ,  $\tau \in [0, 1]$ , such that for  $\tau = 1$ ,  $A_1 = A$  (our operator); for  $\tau = 0$ ,  $A_0$  is a simple operator, whose topological degree  $\gamma(A_0, \Omega)$  can be determined and  $\gamma(A_0, \Omega) \neq 0$ . By the definition of topological degree, if the equation  $A_\tau u = 0$  does not admit solutions at the boundary  $\partial\Omega$  of  $\Omega$ , then the topological degree does not depend on  $\tau$ , i.e.  $\gamma(A_1, \Omega) = \gamma(A_0, \Omega)$ . So  $\gamma(A, \Omega) \neq 0$ . From the above property it follows that the equation  $Au = 0$  has at least one solution in  $\Omega$ .

To verify that equation  $A_\tau u = 0$  does not admit solutions on  $\partial\Omega$ , it suffices to prove a priori estimates: we show that for any solution  $u$  of this equation, we have  $\|u\|_E < R$  for some  $R > 0$ . This means that the equation  $A_\tau u = 0$  has not solutions on the boundary of the ball  $B(0, R) \subset E$ , neither outside it. If  $B(0, R) \subseteq \Omega$ , then equation  $A_\tau u = 0$  does not admit solutions on the boundary  $\partial\Omega$  of  $\Omega$ .

The structure of the paper is the following. In the next section we introduce a class of homotopies  $A_\tau$ ,  $\tau \in [0, 1]$  and obtain some auxiliary results. The boundedness and the sign of the wave speed are studied in Section 3. A priori estimates of the solutions of (1.4) are obtained in Section 4. The main result on the existence of travelling waves is also proved here.

### 2. Estimates of the Solutions

In [2], the Fredholm property and the properness of the integro-differential operator  $A$  depending on a parameter  $\tau \in [0, 1]$ , have been studied in weighted Hölder spaces. Denote by  $A_\tau$  the operator  $A$  for  $c$  and  $J$  depending on  $\tau \in [0, 1]$ , that is  $A_\tau : E_\mu \rightarrow E_\mu^0$ ,

$$A_\tau u = (u + \psi)'' + c(\tau)(u + \psi)' + F(u + \psi, J_\tau(u + \psi)). \tag{2.1}$$

The properness of  $A_\tau$  and its Fredholm property in the weighted spaces  $E_\mu$  and  $E_\mu^0$  have allowed one to define the topological degree in [2]. These results will be applied in the present paper to the study of travelling wave solutions of equation (1.1) in the bistable case, for  $F(w, J(w)) = f(w)J(w) - g(w)$ . In (2.1) we take  $F(w, J_\tau(w)) = f(w)J_\tau(w) - g(w)$ , where

$$J_\tau(w) = \int_{-\infty}^{\infty} \phi_\tau(x-y)u(y)dy, \quad \phi_\tau(x) = \frac{(\varepsilon_0 - 1)\tau + 1}{\varepsilon_0} \phi\left(\frac{(\varepsilon_0 - 1)\tau + 1}{\varepsilon_0}x\right), \tag{2.2}$$

for  $\varepsilon_0 > 0$  small enough. Remark that for  $\tau = 1$ ,  $A_1 u \equiv Au$ . We study here the problem

$$w'' + c(\tau)w' + f(w)J_\tau(w) - g(w) = 0, \tag{2.3}$$

$$\lim_{x \rightarrow \pm\infty} w(x) = w^\pm. \tag{2.4}$$

Suppose that  $f, g \in C^1(\mathbb{R})$  and that (1.3) holds. The linearization of  $A_\tau$  about a function  $u_1 \in E_\mu$  is the operator  $L_\tau : E_\mu \rightarrow E_\mu^0$ ,

$$L_\tau u \equiv A'_\tau(u_1)u = u'' + c(\tau)u' + \frac{\partial F}{\partial u}(u_1 + \psi, J_\tau(u_1 + \psi))u + \frac{\partial F}{\partial U}(u_1 + \psi, J_\tau(u_1 + \psi))J_\tau(u), \tag{2.5}$$

where  $\partial F/\partial u$  and  $\partial F/\partial U$  are the derivatives of  $F(u, U)$  with respect to the first and to the second variable, respectively.

For the linearized operator  $L_\tau$ , we introduce the limiting operators. For  $w_1 = u_1 + \psi$  there exist the limits  $\lim_{x \rightarrow \pm\infty} w_1(x) = w^\pm$ , hence  $J_\tau(w_1) = J_\tau(u_1 + \psi) \rightarrow w^\pm$  as  $x \rightarrow \pm\infty$  and the limiting operators associated to  $L_\tau$  are given by

$$L_\tau^\pm u = u'' + c(\tau)u' + a^\pm u + b^\pm J_\tau(u), \tag{2.6}$$

where

$$a^\pm = \frac{\partial F}{\partial u}(w^\pm, w^\pm) = f'(w^\pm)w^\pm - g'(w^\pm), \quad b^\pm = \frac{\partial F}{\partial U}(w^\pm, w^\pm) = f(w^\pm).$$

In this section, we give some auxiliary results on the solutions of problem (2.3) – (2.4). First we recall a result for the linear parabolic problem

$$\frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} + a(x, t) J_\tau(v) + b(x, t) v, \quad v(x, 0) = v_0(x), \quad x \in \mathbb{R}. \quad (2.7)$$

**Lemma 1.** (see [3]) *Assume that  $a$  and  $b$  are continuous functions such that  $a(x, t) \geq 0$ , for all  $x, t \in \mathbb{R}$  and  $a(x, t) + b(x, t) < 0$  for  $|x|$  large enough and  $t \in [0, T]$ , for some  $T > 0$ . If  $v_0(x) \geq 0$  on  $\mathbb{R}$  and  $v_0 \neq 0$  (not identically 0), then  $v(x, t) > 0$  for any  $x \in \mathbb{R}$  and  $t \in [0, T]$ .*

One now proves that every nonincreasing solution of (2.3)–(2.4) is in fact strictly decreasing on  $\mathbb{R}$ .

**Lemma 2.** *One supposes that  $f(w) \geq 0$ ,  $(\forall) w \in [w^+, w^-]$  and (1.3) holds. Let  $w_0$  be a non-constant and nonincreasing on  $\mathbb{R}$  solution of problem (2.3) – (2.4). Then  $w_0$  is strictly decreasing on  $\mathbb{R}$ .*

*Proof.* One differentiates (2.3), uses the change of function  $w' = -v$  and employs the equality  $(J_\tau(w))' = J_\tau(w')$  to deduce that

$$\begin{aligned} v'' + c(\tau) v' + a(x) J_\tau(v) + b(x) v &= 0, \\ a(x) &= f(w), \\ b(x) &= J_\tau(w) f'(w) - g'(w). \end{aligned} \quad (2.8)$$

Here  $a = f(w) \geq 0$ ,  $(\forall) w \in [w^+, w^-]$  and by (1.3),  $a(x) + b(x) = f(w) + J_\tau(w) f'(w) - g'(w) < 0$  for  $|x|$  large enough.

Let  $v_0$  be a solution of (2.8),  $v_0 \geq 0$ ,  $v_0 \neq 0$ . We show that  $v'_0 > 0$  on  $\mathbb{R}$ . Applying Lemma 1 for problem (2.7) with the initial condition  $v_0$  above and observing that any travelling wave of (2.7) is a solution of (2.8), it follows that  $v_0 > 0$  on  $\mathbb{R}$ , i. e.  $w'_0 < 0$  on  $\mathbb{R}$ , as claimed.

**Lemma 3.** *Assume that  $f(w) \geq 0$  for  $w \in [w^+, w^-]$ . Let  $w_j$  be a sequence of solutions of problem (2.3) – (2.4) such that  $w_j \rightarrow w_0$  in  $C^1(\mathbb{R})$ , with  $w^+ < w_0(x) < w^-$  and  $w'_0(x) \leq 0$ ,  $(\forall) x \in \mathbb{R}$ . Then for  $j$  large enough, we have  $w^+ < w_j(x) < w^-$  and  $w'_j(x) < 0$ ,  $(\forall) x \in \mathbb{R}$ .*

*Proof.* Let us first show that  $w^+ < w_j(x)$ ,  $(\forall) x \in \mathbb{R}$ ,  $j$  large enough. Supposing by contradiction that this does not happen, it follows that  $W_j(x) = w_j(x) - w^+$  has a negative minimum in some point  $x_j$ . Thus

$$W_j(x_j) < 0, \quad W'_j(x_j) = 0, \quad W''_j(x_j) \geq 0.$$

Moreover, by the uniform convergence  $W_j \rightarrow w_0 - w^+$  (as  $j \rightarrow \infty$ ) and  $w_0 - w^+ > 0$ ,  $w_0(x) \rightarrow w^+$  as  $x \rightarrow \infty$ , we derive that for each given interval  $[a, b]$  of  $x$ ,  $W_j(x) > 0$  for  $j$  sufficiently large. Hence if the functions  $W_j(x)$  have negative values,

then the corresponding  $x$  should go to  $+\infty$ . Thus  $x_j \rightarrow +\infty$  and  $J_\tau(W_j)(x_j) \rightarrow J_\tau(w_0 - w^+)(+\infty) = 0$ . Then

$$W_j'' + c(\tau)W_j' + J_\tau(w_j)f(w_j) - g(w_j) - w^+f(w^+) + g(w^+) = 0.$$

At the point  $x = x_j$  we have

$$W_j''(x_j) + c(\tau)W_j'(x_j) + J_\tau(W_j)(x_j)f(w_j(x_j)) + w^+[f(w_j(x_j)) - f(w^+)] - [g(w_j(x_j)) - g(w^+)] = 0. \tag{2.9}$$

We can write

$$\begin{cases} f(w_j(x_j)) - f(w^+) = f'(w^+)[w_j(x_j) - w^+] + \alpha_j[w_j(x_j) - w^+] \\ g(w_j(x_j)) - g(w^+) = g'(w^+)[w_j(x_j) - w^+] + \beta_j[w_j(x_j) - w^+] \end{cases},$$

with  $\alpha_j, \beta_j \rightarrow 0$  as  $x_j \rightarrow +\infty$ . Then (2.9) can be written as

$$W_j''(x_j) + c(\tau)W_j'(x_j) + J_\tau(W_j)(x_j)f(w_j(x_j)) - W_j(x_j)f(w^+) + [f(w^+) + w^+f'(w^+) - g'(w^+)]W_j(x_j) + (w^+\alpha_j - \beta_j)W_j(x_j) = 0. \tag{2.10}$$

By

$$J_\tau(W_j)(x_j) = \int_{-\infty}^{\infty} \phi(x_j - y)W_j(y)dy \geq \int_{-\infty}^{\infty} \phi(x_j - y)W_j(x_j)dy = W_j(x_j), \tag{2.11}$$

and

$$\begin{aligned} J_\tau(W_j)(x_j)f(w_j(x_j)) - W_j(x_j)f(w^+) \\ = [J_\tau(W_j)(x_j) - W_j(x_j)]f(w_j(x_j)) + W_j^2(x_j)(f'(w^+) + \alpha_j), \end{aligned}$$

equation (2.10) can be written as

$$\begin{aligned} W_j''(x_j) + c(\tau)W_j'(x_j) + [J_\tau(W_j)(x_j) - W_j(x_j)]f(w_j(x_j)) \\ + [f(w^+) + w^+f'(w^+) - g'(w^+)]W_j(x_j) + W_j^2(x_j)(f'(w^+) + \alpha_j) \\ (w^+\alpha_j - \beta_j)W_j(x_j) = 0. \end{aligned}$$

Since  $W_j^2(x_j) \rightarrow 0$ ,  $(w^+\alpha_j - \beta_j)W_j(x_j) \rightarrow 0$  faster than  $W_j(x_j) \rightarrow 0$ , then with the aid of (1.3), (2.11) and  $W_j(x_j) < 0$ ,  $W_j'(x_j) = 0$ ,  $W_j''(x_j) \geq 0$ , we obtain a contradiction in signs. Therefore,  $w^+ < w_j(x)$  for all  $x \in \mathbb{R}$  and all  $j$  large enough. Similarly  $w_j(x) < w^-$  for all  $x \in \mathbb{R}$  and all  $j$  large enough.

We now prove that  $w_j'(x) < 0$ ,  $(\forall) x \in \mathbb{R}$ . Assume that this is not true, i. e. there exists  $x_j \in \mathbb{R}$  such that  $w_j'(x_j) = 0$ .

If  $x_j$  is bounded, then  $x_j \rightarrow x_0$  on a subsequence and since  $w_j \rightarrow w_0$  in  $C^1(\mathbb{R})$ , we derive that  $w'_0(x_0) = 0$ . This contradicts Lemma 2.

If  $x_j \rightarrow \pm\infty$ , then differentiating (2.3) and denoting  $v = -w'$ , one obtains like in the proof of Lemma 2 that

$$v'' + c(\tau)v' + a(x)J_\tau(v) + b(x)v = 0, \quad a(x) = f(w(x)), \quad b(x) = J_\tau(w)f'(w) - g'(w).$$

If  $v_j(x) \geq 0$  for all  $x \in \mathbb{R}$ , from  $v_j(x_j) = 0$  we arrive again at a contradiction with Lemma 2. This implies that each  $v_j$  has also negative values. On the other hand, by  $w'_j \rightarrow w'_0$  uniformly on  $\mathbb{R}$  and  $w'_0 < 0$  on  $\mathbb{R}$ , we obtain that  $v_j$  is positive in every bounded interval  $[a, b]$  of  $x$ , for  $j$  large enough. Since  $w_j(x)$  has finite limits as  $x \rightarrow \pm\infty$ , we get  $v_j(x) \rightarrow 0$  as  $x \rightarrow \pm\infty$ . Therefore, the minimum value of  $v_j(x)$ , which is obviously negative, is reached at some  $\hat{x}_j \rightarrow \infty$ . So  $v_j(\hat{x}_j) < 0$  and by the uniform convergence  $w'_j(x) \rightarrow w'_0(x)$  and  $w_0 \rightarrow w^\pm$ , we find that  $v_j(\hat{x}_j) \rightarrow 0$  as  $j \rightarrow \infty$ .

Set  $\delta = v_j(\hat{x}_j)$  and  $V_j(x) = v_j(x) - \delta$ . Observe that  $V_j(x) \geq 0$  on  $\mathbb{R}$ ,  $V_j(\hat{x}_j) = 0$  and

$$V_j'' + c(\tau)V_j' + a(x)J_\tau(V_j) + b(x)V_j + [a(x) + b(x)]\delta = 0. \tag{2.12}$$

Since  $\hat{x}_j$  is a point of minimum for  $V_j$ , it follows that  $V_j''(\hat{x}_j) \geq 0$ ,  $V_j(\hat{x}_j) = 0$ ,  $J_\tau(V_j)(\hat{x}_j) \geq 0$ . In addition, if  $\hat{x}_j \rightarrow \pm\infty$ , then

$$\begin{aligned} a(\hat{x}_j) + b(\hat{x}_j) &= f(w(\hat{x}_j)) + J_\tau(w_j)(\hat{x}_j)f'(w_j(\hat{x}_j)) - g'(w_j(\hat{x}_j)) \\ &\rightarrow f(w^\pm) + w^\pm f'(w^\pm) - g'(w^\pm) < 0 \end{aligned}$$

via (1.3). Hence  $a(\hat{x}_j) + b(\hat{x}_j) < 0$  for  $j$  large enough and  $a(\hat{x}_j) > 0$  for all  $j$ .

Thus we arrive at a contradiction in signs in equation (2.12). The lemma is proved.

Since  $f, g$  are bounded functions on  $[w^+, w^-]$ , as in Lemma 6 from [3] we can easily obtain the boundedness of the derivatives  $w', w''$ .

**Lemma 4.** *If the solution  $w$  of equation (2.3) satisfies the estimate  $|w(x)| \leq R$ ,  $(\forall) x \in \mathbb{R}$ , then  $|w'(x)| \leq C$ ,  $|w''(x)| \leq C$ ,  $(\forall) x \in \mathbb{R}$ , where  $C > 0$  is a constant depending on  $R$  and the bounds for  $f$  and  $g$ .*

### 3. Estimates of the Wave Speed

In the following we find estimates independent of  $\tau$  for the wave speed  $c(\tau)$ .

**Theorem 5.** *If  $w(x)$  is a monotonically decreasing solution of problem (2.3) – (2.4) and  $c(\tau)$  is the corresponding wave speed, then there exist some constants  $c_1, c_2$  independent of  $\tau$ , such that  $c_1 < c(\tau) < c_2$ ,  $(\forall) \tau \in [0, 1]$ .*

*Proof.* Recall that  $w(x)$  is a traveling wave solution of the integro-differential equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + J_\tau(u) f(u) - g(u).$$

Denote by  $u(x, t)$  another solution of this equation, monotone with respect to  $x$ , having the limits  $w^\pm$  at  $\pm\infty$ . We will estimate first this solution from above. Denote by  $w^* \in (w^+, w^-)$  the unstable stationary solution of the equation  $dw/dt = wf(w) - g(w)$ , i. e.  $w^* f(w^*) - g(w^*) = 0$ . There exist two constants  $a > 0, b \in \mathbb{R}$  such that

$$G(u) = J_\tau(u) f(u) - g(u) \leq aJ_\eta(u - w^*) + b(u - w^*), \quad w^* \leq u \leq w^-, \quad (3.1)$$

where  $\eta(x)$  is a piece-wise constant function, equal  $M = \sup_x \phi(x)$  in the support  $[-N, N]$  of  $\phi$  and zero otherwise and

$$J_\eta(z) = \int_{-\infty}^{\infty} \eta(x - y) z(y, t) dy.$$

Indeed,

$$\begin{aligned} G(u) &= f(u) J_\tau(u - w^*) + w^* [f(u) - f(w^*)] - [g(u) - g(w^*)] \\ &= f(u) J_\tau(u - w^*) + (u - w^*) (w^* f'(\xi_1) - g'(\xi_2)), \end{aligned}$$

for  $\xi_1, \xi_2 \in (w^*, w^-)$  intermediate points. Since  $f \geq 0, f, f', g'$  are bounded on  $[w^*, w^-]$  and  $J_\tau(u - w^*) \leq J_\eta(u - w^*)$ , we easily arrive at (3.1).

Consider now the auxiliary equation

$$\frac{\partial \hat{u}}{\partial t} = \frac{\partial^2 \hat{u}}{\partial x^2} + aJ_\eta(\hat{u} - w^*) + b(\hat{u} - w^*) \quad (3.2)$$

with the initial condition

$$\hat{u}(x, 0) \geq \max(w^*, u(x, 0)).$$

We look for a solution of equation (3.2) in the form  $\hat{u}(x, t) = w^* + e^{-\lambda(x-c_2t)}$ . Then  $\lambda$  verifies the equation

$$\lambda^2 - c_2\lambda + Ma \frac{e^{\lambda N} - e^{-\lambda N}}{\lambda} + b = 0.$$

For  $c_2$  large enough, there exists  $\lambda > 0$  solution of this equation and, consequently  $\hat{u}(x, t) = w^* + e^{-\lambda(x-c_2t)}$  is a solution of (3.2).

By a comparison theorem, we obtain that  $\hat{u}(x, t) \geq w^*, \hat{u}(x, t) \geq u(x, t)$ , for all  $x \in \mathbb{R}$  and  $t \geq 0$ , and by (3.1) we have also  $G(\hat{u}(x, t)) \leq aJ_\eta(\hat{u} - w^*) + b(\hat{u} - w^*)$ . If we chose  $u(x, 0) = w(x)$ , we obtain  $u(x, t) \equiv w(x - c(\tau)t) \leq \hat{u}(x, t)$ . Similarly one can find an estimate from below for  $w(x)$ . If  $c(\tau)$  is the speed of propagation



of  $w(x)$ , this implies that  $c_1 \leq c(\tau) \leq c_2$ , where  $c_1, c_2$  are some fixed values. The proof is complete.

We are going to establish the sign of the speed  $c(\tau)$ . We show that the waves connecting a stable point with an unstable one can exist only for a specific sign of the speed. Recall first an auxiliary result from [3].

**Lemma 6.** (see [3]) *Let  $\phi$  be non-negative and even. If  $v$  is a decreasing positive function, then for each  $N$*

$$\int_N^\infty [J_\tau(v)(x) - v(x)] dx \geq 0.$$

*If  $v$  is an increasing positive function, then for each  $N$*

$$\int_{-\infty}^N [J_\tau(v)(x) - v(x)] dx \geq 0.$$

**Lemma 7.** *Assume that  $\phi$  is an even and non-negative function and  $w$  is a decreasing solution of equation (2.3).*

*If  $w$  has the limits  $w(-\infty) = w^-, w(+\infty) = w^*$ , then  $c(\tau) > 0$  on  $[0, 1]$ .*

*If  $w$  has the limits  $w(-\infty) = w^*, w(+\infty) = w^+$ , then  $c(\tau) < 0$  on  $[0, 1]$ .*

*Proof.* Let  $w$  be a decreasing solution of (2.3) with the limits  $w(-\infty) = w^-, w(+\infty) = w^*$ . Set  $v(x) = w(x) - w^*$ . Then (2.3) becomes

$$v'' + c(\tau)v' + J_\tau(v)f(v+w^*) + w^*[f(v+w^*) - f(w^*)] - [g(v+w^*) - g(w^*)] = 0.$$

Writing the square brackets in the form

$$\begin{cases} f(v+w^*) - f(w^*) = v f'(w^*) + \alpha v \\ g(v+w^*) - g(w^*) = v g'(w^*) + \beta v \end{cases}, \tag{3.3}$$

with  $\alpha(x) \rightarrow 0, \beta(x) \rightarrow 0$  as  $x \rightarrow \infty$ , the above equality can be written as

$$v'' + c(\tau)v' + J_\tau(v)f(v+w^*) + v[w^*f'(w^*) - g'(w^*)] + v(\alpha w^* - \beta) = 0.$$

Integrating with respect to  $x$  from  $N$  to  $+\infty$ , with  $N$  large enough, with the aid of (3.3) one arrives at

$$\begin{aligned} -v'(N) - c(\tau)v(N) + \int_N^\infty J_\tau(v)v[f'(w^*) + \alpha] dx + f(w^*) \int_N^\infty J_\tau(v) dx \\ + [w^*f'(w^*) - g'(w^*)] \int_N^\infty v(x) dx + \int_N^\infty v(\alpha w^* - \beta) dx = 0. \end{aligned} \tag{3.4}$$

In view of (1.3) and of Lemma 6, we have

$$f(w^*) \int_N^\infty J_\tau(v) dx + [w^*f'(w^*) - g'(w^*)] \int_N^\infty v(x) dx \geq$$

$$f(w^*) \int_N^\infty [J_\tau(v)(x) - v(x)] dx \geq 0.$$

Next,  $v'(N) < 0$ ,  $v(N) > 0$  and all the other integrals from (3.4) are small for  $N$  sufficiently large. This is not possible except for the situation when  $c(\tau) > 0$ ,  $(\forall) \tau \in [0, 1]$ . The second assertion follows in a similar way.

#### 4. A Priori Estimates of Monotone Solutions of Problem (2.3)-(2.4)

First we show that monotone solutions of problem (2.3) – (2.4) have an exponential behavior at infinity.

**Lemma 8.** *Let  $w_\tau$  be a monotonically decreasing solution of (2.3)–(2.4). There exists a constant  $\varepsilon > 0$  such that for all  $x$  that satisfy  $|w_\tau(x) - w^+| \leq \varepsilon$ , we have in fact*

$$|w_\tau(x) - w^+| \leq Ke^{-ax}.$$

Analogously, for such  $x$  that  $|w_\tau(x) - w^-| \leq \varepsilon$ , the estimate

$$|w_\tau(x) - w^-| \leq Ke^{-bx}$$

holds. Here, the constants  $K, a, b > 0$  are independent of  $\tau$  and  $w_\tau$ .

*Proof.* Let  $W(x) = w_\tau(x) - w^+$ . Then  $W(x) \geq 0$ ,  $W$  is decreasing and

$$W'' + c(\tau)W' + J_\tau(W)f(w_\tau) + w^+[f(w_\tau) - f(w^+)] - [g(w_\tau) - g(w^+)] = 0.$$

Using estimates similar to (3.3) this equality becomes

$$W'' + c(\tau)W' + [J_\tau(W)f(w_\tau) - Wf(w^+)] + [f(w^+) + w^+f'(w^+) - g'(w^+)]W + (w^+\alpha - \beta)W = 0. \quad (4.1)$$

In order to estimate  $J_\tau(W)f(w_\tau) - Wf(w^+)$ , we write

$$\begin{aligned} J_\tau(W)f(w_\tau) - Wf(w^+) &= J_\tau(W)f(w^+ + W) - Wf(w^+) \\ &= J_\tau(W)(f(w^+) + f'(\tilde{w})W) - Wf(w^+) = (J_\tau(W) - W)f(w^+) + J_\tau(W)f'(\tilde{w})W, \end{aligned}$$

where  $\tilde{w}$  is some intermediate point. Then equation (4.1) becomes

$$\begin{aligned} W'' + c(\tau)W' + (J_\tau(W) - W)f(w^+) + J_\tau(W)f'(\tilde{w})W \\ + [f(w^+) + w^+f'(w^+) - g'(w^+)]W + (\alpha w^+ - \beta)W = 0 \end{aligned}$$

or

$$W'' + c(\tau)W' + J_\tau(W)f(w^+) + (w^+f'(w^+) - g'(w^+) + \sigma(x))W = 0, \quad (4.2)$$

where

$$\sigma(x) = J_\tau(W)f'(\tilde{w}) + (\alpha w^+ - \beta) \rightarrow 0, \quad x \rightarrow \infty.$$

Hence, the corresponding limiting equation is

$$W'' + c(\tau)W' + J_\tau(W)f(w^+) + (w^+f'(w^+) - g'(w^+))W = 0.$$

By virtue of conditions (1.3), this limiting equation does not have nonzero bounded solutions. Hence the operator from the left-hand side of (4.2) is a Fredholm operator and therefore  $W(x)$  decays exponentially at infinity. The estimate can be obtained independent of  $\tau$  since  $\tau$  changes on a compact interval. The lemma is proved.

**Lemma 9.** *Let  $\varepsilon > 0$  be the constant from Lemma 8. Then there exists a constant  $\chi > 0$  such that, for any monotone solution  $w_\tau$  of problem (2.3) – (2.4) and for any  $x$  with  $|w_\tau(x) - w^+| > \varepsilon$  and  $|w_\tau(x) - w^-| > \varepsilon$ , we have  $|w'_\tau(x)| \geq \chi$ . Constant  $\chi$  is independent of  $\tau$  and of  $w_\tau$ .*

The proof of the lemma is similar to the proof in [3], so we omit it.

**Lemma 10.** *For any given  $r \geq 0$ , denote by  $\mathcal{M}_r$  the set of all monotone solutions  $w$  of problem (2.3) – (2.4),  $\tau \in [0, 1]$ , such that  $|x_w| \leq r$ , where  $x_w$  is the solution of equation  $w_\tau(x_w) = w_0$ . In this case, there is  $C_r > 0$  such that, for every  $w \in \mathcal{M}_r$ , we have*

$$\|w - \psi\|_{E_\mu} \leq C_r.$$

*Proof.* Let  $0 < \varepsilon < w_0$ ,  $\chi > 0$  be the constants arising in Lemmas 8 and 9 respectively,  $r \geq 0$  be arbitrarily fixed, and  $w \in \mathcal{M}_r$ . Consider  $x_1, x_2$  such that

$$w^- - w(x_1) = \varepsilon, \quad w(x_2) - w^+ = \varepsilon. \tag{4.3}$$

Then  $x_1 < x_w < x_2$  and  $|x_w| \leq r$ . By Lemma 8 we know that outside  $[x_1, x_2]$ ,  $w - \psi$  has an exponential behavior, i. e.

$$\|w - \psi\|_{E_\mu} = \|w - \psi\|_{E_\mu([x_1, x_2])},$$

where  $E_\mu([x_1, x_2])$  is  $C^{2+\alpha}([x_1, x_2])$  with the weight  $\mu$ . It remains to prove that  $\|w - \psi\|_{E_\mu([x_1, x_2])} \leq C_r$  for some  $C_r > 0$ . Observe that

$$|w(x_2) - w(x_1)| = |w'(\xi)|(x_2 - x_1) \geq \chi(x_2 - x_1),$$

where  $\xi \in (x_1, x_2)$  is an intermediate point. Hence

$$\chi(x_2 - x_1) \leq w(x_1) - w(x_2) = w^- - w^+ - 2\varepsilon < w^- - w^+,$$

$$\begin{cases} |x_1| \leq |x_1 - x_w| + |x_w| \leq |x_1 - x_2| + |x_w| \leq N + r \\ |x_2| \leq |x_2 - x_w| + |x_w| \leq |x_2 - x_1| + |x_w| \leq N + r \end{cases} ,$$

where  $N = (w^- - w^+) / \chi$ . Then,

$$\begin{aligned} \|w - \psi\|_{E_\mu([x_1, x_2])} &= \|(w - \psi) \mu\|_{C^{2+\alpha}([x_1, x_2])} = \|(w - \psi) \mu\|_{C^\alpha([x_1, x_2])} + \\ &\|[(w - \psi) \mu]'\|_{C^\alpha([x_1, x_2])} + \|[(w - \psi) \mu]''\|_{C^\alpha([x_1, x_2])}. \end{aligned}$$

We estimate now each norm:

$$\begin{aligned} \|(w - \psi) \mu\|_{C^\alpha([x_1, x_2])} \\ \leq \|w - \psi\|_{C^\alpha([x_1, x_2])} \|\mu\|_{C([x_1, x_2])} + \|\mu\|_{C^\alpha([x_1, x_2])} \|w - \psi\|_{C([x_1, x_2])}. \end{aligned}$$

Analogously for the first and the second derivative. Therefore, there exists  $C_r > 0$  in order that  $\|w - \psi\|_{E_\mu} \leq C_r$ , as claimed. The lemma is proved.

**Proposition 11.** Denote by  $w_M$  and  $w_N$  any monotone and any nonmonotone solution of problem (2.3) – (2.4), respectively.

a) There exists  $R > 0$  such that  $\|w_M - \psi\|_{E_\mu} \leq R$ ;

b) There exists  $r > 0$  such that  $\|w_M - w_N\|_{E_\mu} \geq r$ . In other words, we can separate monotone solutions of (2.3) – (2.4) from nonmonotone solutions.

*Proof.* Consider the wave speed  $c$  depending on  $u$ , where  $u(x) = w(x) - \psi(x)$ . Denote the solution of the equation  $w(x) = w_0$  by  $x_w$ .

a) We show the existence of some  $r > 0$  such that all monotone solutions  $w$  of problem (2.3) – (2.4) with  $c = c(u)$  belong to  $\mathcal{M}_r$  from Lemma 10, that is  $|x_w| \leq r$ . Assume by contradiction that there exist two sequences  $x_k$  and  $w_k(x)$ , such that  $w_k(x_k) = w_0$  and  $|x_k| \rightarrow \infty$ . Let  $u_k(x) = w_k(x) - \psi(x)$ ,  $c = c(u_k)$  the corresponding wave speed, and

$$v_k(x) = w_k(x + x_k) - \psi(x).$$

Remark that  $v_k + \psi \in \mathcal{M}_0$  which is  $\mathcal{M}_r$  for  $r = 0$  and  $x_w = 0$ . Then, by Lemma 10, one derives that

$$\|v_k\|_{E_\mu} = \|w_k - \psi\|_{E_\mu} \leq C_0, \tag{4.4}$$

for some  $C_0 > 0$ . Let  $\gamma$  be an increasing function satisfying the conditions  $\gamma(-\infty) = 0$ ,  $\gamma(\infty) = 1$ ,  $\int_{-\infty}^0 \gamma(x) dx < \infty$ , and let  $c(u) = \ln \rho(u)$ , where  $\rho(u)$  is the integral

$$\rho(u) = \left( \int_{-\infty}^{\infty} (u(x) + \psi(x) - w^+)^2 \gamma(x) dx \right)^{1/2}.$$

Making the change of variable  $x + x_k = y$ , we get

$$\rho(u_k) = \left( \int_{-\infty}^{\infty} (v_k(x) + \psi(x) - w^+)^2 \gamma(x + x_k) dx \right)^{1/2}.$$

We now find the limits of  $\rho(u_k)$  as  $x_k \rightarrow \infty$  and as  $x_k \rightarrow -\infty$ . If  $x_k \rightarrow \infty$ , then  $\gamma(x + x_k) \rightarrow 1$ ,  $|v_k| \rightarrow 0$  and  $\psi(x) - w^+$  does not approach 0 when  $x$  is in a neighbourhood of  $-\infty$ . So,  $\rho(u_k) \rightarrow \infty$ . If  $x_k \rightarrow -\infty$ , then  $\gamma(x + x_k) \rightarrow 0$  and  $\psi, v_k$  are bounded by functions from  $L^2(\mathbb{R})$ . For  $v_k$  this follows from (4.4). So  $\rho(u_k) \rightarrow 0$ . Now we can conclude that  $c(u_k) = \ln \rho(u_k)$  tends to  $\infty$  as  $x_k \rightarrow \infty$  and tends to  $-\infty$  as  $x_k \rightarrow -\infty$ . This contradicts the boundedness of  $c(u)$  (see Theorem 5). Thus we have proved that  $w \in \mathcal{M}_r$  for some  $r > 0$ . The claim follows by Lemma 10.

b) If  $w_M$  and  $w_N$  are arbitrary monotone and nonmonotone solutions of problem (2.3) – (2.4), respectively, denote

$$u_M = w_M - \psi, \quad u_N = w_N - \psi.$$

Assume that conclusion of part b) is not true. Then at least on some sequences  $u_M^k, u_N^k$  we have

$$\|u_M^k - u_N^k\|_{E_\mu} \rightarrow 0 \text{ as } k \rightarrow \infty. \tag{4.5}$$

By part a) of the proposition, at least on a subsequence denoted again  $k$ ,  $u_M^k$  is strongly convergent in  $C_\mu^2(\mathbb{R})$  to some limit  $u_M^0 \in E_\mu : \|u_M^k - u_M^0\|_{C_\mu^2(\mathbb{R})} \rightarrow 0$  as  $k \rightarrow \infty$ . Then,  $w^0 = u_M^0 + \psi$  is a solution of (2.3) – (2.4) for some  $\tau \in [0, 1]$  and  $c$  and

$$\|w_M^k - w^0\|_{C_\mu^2(\mathbb{R})} = \|u_M^k - u_M^0\|_{C_\mu^2(\mathbb{R})} \rightarrow 0 \text{ as } k \rightarrow \infty. \tag{4.6}$$

Now from (4.5) and (4.6), one deduces that

$$\|w_N^k - w^0\|_{C_\mu^2(\mathbb{R})} = \|u_N^k + \psi - w^0\|_{C_\mu^2(\mathbb{R})} \leq \|u_N^k - u_M^k\|_{C_\mu^2(\mathbb{R})} + \|w_M^k - w^0\|_{C_\mu^2(\mathbb{R})} \rightarrow 0 \text{ as } k \rightarrow \infty.$$

Since  $w_N^k \rightarrow w^0$  in  $C^1$  and  $w^0$  is nonincreasing (as the limit of the sequence of nonincreasing solutions  $w_M^k = u_M^k + \psi$ ), Lemma 3 leads to  $(w_N^k)'(x) < 0$  on  $\mathbb{R}$  for  $N$  large enough. But  $w_N^k$  is a nonmonotone solution. This contradiction ends the proof.

**Theorem 12.** *There exists a monotone travelling wave solution of problem (1.4) – (1.5) where the function  $F(w, J(w)) = f(w)J(w) - g(w)$  satisfies (1.7), that is a constant  $c$  and a monotone function  $w \in C^2(\mathbb{R})$ , satisfying equation (1.4) and the limits (1.5).*

*Proof.* First we separate monotone solutions of problem (2.3) – (2.4) from nonmonotone solutions. To this end, consider a ball in  $E_\mu$ , say  $\|u\|_{E_\mu} \leq R$ , which contains all solutions of equation (2.3), both monotone and nonmonotone. Proposition 11 assures the existence of some  $r > 0$  in order that for all solutions of (2.3) from the ball  $\|u\|_{E_\mu} \leq R + 1$ , we have

$$\|w_M - w_N\|_{E_\mu} \geq r.$$

In [2] we have shown that operator  $A_\tau(u)$  is proper with respect to  $\tau$  and  $u$ . In other words, the set of all solutions of equation  $A_\tau(u) = 0$  is compact in the ball  $\|u\|_{E_\mu} \leq R + 1$ . Therefore, from any covering of the set of monotone solutions  $u_M$  by open balls  $B(u_M, r)$  (with the center at  $u_M$  and the radius  $r$ ), we can select a finite subcovering. Denote by  $G_k$ ,  $k = 1, \dots, N$ , the set of domains formed by the union of the balls of this subcovering and by  $\partial G_k$  their boundaries. Obviously, any monotone solution  $u_M \in \bigcup_{k=1}^N G_k$ , for every  $\tau \in [0, 1]$ , while any nonmonotone solution  $u_N \notin \bigcup_{k=1}^N (G_k \cup \partial G_k)$ . Thus we have separated monotone from nonmonotone solutions of equation (2.3).

In paper [2] a topological degree is constructed for the general  $\tau$ -dependent operators  $A_\tau$  in (2.1). This is available in particular for operators  $A_\tau$  with  $F(w, J_\tau(w)) = f(w)J_\tau(w) - g(w)$ , where  $\phi_\tau, J_\tau$  are defined in (2.2). In [1] it is proved that the topological degree for the particular case of the operator  $A_0$  (where the support of  $\phi$  is narrow) equals 1. In the present paper, we have got a priori estimates for the solutions of (2.3) – (2.4) (Proposition 11). Consequently, one can use Leray-Schauder method to study the existence of travelling wave solutions for (1.4) – (1.5). Since the topological degree does not change under a continuous deformation of the operator which does not vanish at the boundary of the domain, it follows that for  $A_1 u = Au$ , it is also 1. Hence we deduce the existence of a monotone travelling wave solution for problem (1.4) – (1.5). This completes the proof.

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